

F a n j u n B u

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I am a Ph.D. student at Cornell Tech, under the supervision of Dr. Wendy Ju. My research focuses on understanding how people interact with emerging technologies. In particular, I am interested in human-robot interaction and the challenges it presents. My approach involves utilizing the Wizard-of-Oz technique for in-the-wild deployments to simulate robots' autonomy and elicit natural interaction behaviors. By leveraging unique interaction data collected through the Wizard-of-Oz technique, I aim to bootstrap robots' social intelligence. Through my research, I aspire to provide valuable guidelines for the design of future technologies that seamlessly integrate into human environments.

E D U C A T I O N

- 2017–2021 **Johns Hopkins University**, Baltimore, MD
Whiting School of Engineering, B.S. in Applied Mathematics and Statistics,
Computer Science, and Cognitive Science.
Whiting School of Engineering, M.S. in Computer Science

P O S I T I O N S

- 2021–Present **PhD Student**, Cornell Tech
Advised by Professor Wendy Ju,
New York, NY
- 2020–2021 **Research Assistant**, Personal Robotics Lab, University of Washington
Advised by Tapomayukh Bhattacharjee (now an assistant professor at Cornell
University),
Online
- 2020–2021 **Research Assistant**, Intuitive Computing Lab, Johns Hopkins University
Advised by Professor Chien-Ming Huang,
Baltimore, Maryland
- Summer 2019 **Research Intern**, Learning Algorithms and System Laboratory (LASA), École
Polytechnique Fédérale de Lausanne
Laussane, Switzerland
- 2017–2021 **Research Assistant**, Honey Lab, Johns Hopkins University University
Advised by Professor Christopher Honey,
Baltimore, MD

TEACHING ASSISTANTSHIPS

- Spring 2023 **INFO5755/INFO6755/CS5755/CS6755. Mobile Human Robot Interaction Design** Cornell Tech.
Develop new labs for students to learn ROS and build mobile robots. (**Outstanding TA Award**)
- Fall 2021 **CS4750/CS5750/ECE4770/MAE4760. Foundations of Robotics.** Cornell University.
Design assignments for students to learn robot kinematics, planning, and control. (**Outstanding TA Award**)
- Fall 2020 **601.457. Computer Graphics.** Johns Hopkins University.
Help students with basic computer graphics operations in C++.
- Fall 2019, Spring 2020 **553.430. Introduction to Statistics.** Johns Hopkins University.
Teach weekly sessions to cover detailed statistical derivations and examples.
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PUBLICATIONS

- Papers Barry Brown, **Fanjun Bu**, Ilan Mandel, Wendy Ju. “Trash in Motion: Emergent interactions with robotic trashcans in a public square”. In: *Proceedings of the CHI Conference on Human Factors in Computing Systems*. 2024, pp. 1–15.
- Fanjun Bu**, Stacey Li, David Goedicke, Mark Colley, Gyanendra Sharma, Wendy Ju. “Portobello: Extending Driving Simulation from the Lab to the Road”. In: *Proceedings of the CHI Conference on Human Factors in Computing Systems*. 2024, pp. 1–13.
- David Goedicke, Alexandra WD Bremers, Sam Lee, **Fanjun Bu**, Hiroshi Yasuda, Wendy Ju. “XR-OOM: MiXed Reality driving simulation with real cars for research and design”. In: *Proceedings of the 2022 CHI Conference on Human Factors in Computing Systems*. 2022, pp. 1–13.
- Jan Ondras, Abrar Anwar, Tong Wu, **Fanjun Bu**, Malte Jung, Jorge Jose Ortiz, Tapomayukh Bhattacharjee. “Human-robot commensality: Bite timing prediction for robot-assisted feeding in groups”. In: *6th Annual Conference on Robot Learning*. 2022.
- Fanjun Bu**, Chien-Ming Huang. “Object permanence through audio-visual representations”. In: *IEEE Access* 9 (2021), pp. 131574–131582.
- Konstantinos Chatzilygeroudis, Bernardo Fichera, Ilaria Lauzana, **Fanjun Bu**, Kunpeng Yao, Farshad Khadivar, Aude Billard. “Benchmark for bimanual robotic manipulation of semi-deformable objects”. In: *IEEE Robotics and Automation Letters* 5.2 (2020), pp. 2443–2450.

Shima Rahimi Moghaddam, **Fanjun Bu**, Christopher J Honey. "Learning Representations from Temporally Smooth Data". In: *arXiv preprint arXiv:2012.06694* (2020).

Demos and Videos **Fanjun Bu**, Ilan Mandel, Wen-Ying Lee, Wendy Ju. "Trash Barrel Robots in the City". In: *Companion of the 2023 ACM/IEEE International Conference on Human-Robot Interaction*. HRI '23. Stockholm, Sweden: Association for Computing Machinery, 2023, pp. 875–877. ISBN: 9781450399708. DOI: [10.1145/3568294.3580206](https://doi.org/10.1145/3568294.3580206). URL: <https://doi.org/10.1145/3568294.3580206>.

Press Abby Hughes, "New Yorkers treat these remote-controlled 'robot' garbage bins like people, say researchers, CBC Radio, August 4, 2023

Catalina Gonella, "These 'trash bots' have been helping keep Brooklyn's Albee Square clean", Gothamist, August 2, 2023

Roger Clark, "Robots helping keep Downtown Brooklyn clean," Spectrum News NYI, August 1, 2023

Patricia Waldron, "(Almost) everyone likes a helpful trash robot," Cornell Chronicle, April 19, 2023.

Ayesha Rascoe, "Researchers released robot trash cans in NYC to see how people would react," National Public Radio (NPR), April 16, 2023.

Mike Snider, "Robots in the Big Apple: Robo-trash cans patrolling New York plaza make friends, creep out some," USA TODAY, April 15, 2023.

Staff, "These robotic trash cans were filmed to test human-robotic interactions. Watch what happened," CNN Business, April 12, 2023.

Evan Ackerman, "Humans (Mostly) Love Trash Robots > Simple robots wander NYC asking for trash and recycling, and it's adorable," IEEE Spectrum, Mar 10, 2023